PATENT COOPERATION TREATY

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INTERNATIONAL PRELIMINARY REPORT ON PATENTABILITY

(Chapter II of the Patent Cooperation Treaty)

(PCT Article 36 and Rule 70)

Applicant's or agent's file reference A3232.WO.209		FOR FURTHER ACTION	See Form PCT/IPEA/416		
International application No.		nternational filing date (day/month/yea 5.07.2004	r) Priority date (day/month/year) 17.07.2003		
PCT/IB2004/002330		•	17.07.2003		
International Patent Classi B67B3/20, B67B3/28	ication (IPC) or natio	nal classification and IPC			
Applicant AZIONARIA COSTRI	JZIONI MACCHI	NE AUTOMATICHE			
This report is the Authority under A	international prelim rticle 35 and transr	ninary examination report, establi nitted to the applicant according	shed by this International Preliminary Examining to Article 36.		
2. This REPORT co	nsists of a total of	5 sheets, including this cover she	pet.		
3. This report is also	accompanied by	ANNEXES, comprising:	the state of the s		
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INTERNATIONAL PRELIMINARY REPORT ON PATENTABILITY

International application No. PCT/IB2004/002330

	Box N	lo. I	Basis of the repo	rt				
1.	With regard to the language , this report is based on the international application in the language in which it we filed, unless otherwise indicated under this item.							
	□ T	☐ This report is based on translations from the original language into the following language , which is the language of a translation furnished for the purposes of:						
		inte	national search (ur	nder Rules 12.3 an ational application				
2.	have i	With regard to the elements* of the international application, this report is based on <i>(replacement sheets which</i> have been furnished to the receiving Office in response to an invitation under Article 14 are referred to in this report as "originally filed" and are not annexed to this report):						
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	Descr	iption	Pages			• .		
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		any table(s) related to sequence listing (specify):						
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INTERNATIONAL PRELIMINARY REPORT ON PATENTABILITY

International application No. PCT/IB2004/002330

Box No. V Reasoned statement under Article 35(2) with regard to novelty, inventive step or industrial applicability; citations and explanations supporting such statement

1-13

1. Statement

Novelty (N) Ye

Yes: Claims

No: Claims

Inventive step (IS) Yes: Claims 1-13

No: Claims

Industrial applicability (IA) Yes: Claims 1-13

No: Claims

2. Citations and explanations (Rule 70.7):

see separate sheet

PCT/IB2004/002330

Re Item V

Reasoned statement with regard to novelty, inventive step or industrial applicability; citations and explanations supporting such statement

Reference is made to the following document:

D1: US-A-4 535 583 (MURANAKA SHIARU ET AL) 20 August 1985 (1985-08-20)

1 INDEPENDENT CLAIM 1

- 1.1 The document D1 is regarded as being the closest prior art to the subject-matter of claim 1, and shows (the references in parentheses applying to this document):

 A capping unit comprising a conveyor (10), a motor (8), capping assemblies provided with gripping mechanisms (13), primary drive means (15, 16) setting a capping assembly in vertical motion and secondary drive means (12) connected to an electronic control device (19) setting a gripping mechanism in rotational motion.
- 1.2 The subject-matter of claim 1 differs from this known capping unit in that the primary drive means comprises an electric motor connected to the electronic control device, and in that the electronic controller comprises a processing block by means of which to vary the operating parameters of each primary and secondary electric motor according to the dimensions of the respective containers.

The subject-matter of claim 1 is therefore new (Article 33(2) PCT).

- 1.3 The problem to be solved by the present invention may be regarded as rendering the capping unit versatile and suitable for use with many types of containers irrespective of their size.
- 1.4 The solution to this problem proposed in claim 1 of the present application is considered as involving an inventive step (Article 33(3) PCT) for the following reasons:

The processing block of the controller provides the possibility to control the primary and secondary electric motors of each capping assembly independently, by means of the operating parameters, according to the dimensions of the containers, therewith, making the capping unit suitable to be used with any type of container.

INTERNATIONAL PRELIMINARY REPORT ON PATENTABILITY (SEPARATE SHEET)

International application No.

PCT/IB2004/002330

2 DEPENDENT CLAIMS 2-13
Claims 2-13 are dependent on claim 1 and as such also meet the requirements of the PCT with respect to novelty and inventive step.

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Claims

A capping unit for closing containers (2) with the type comprising: (3), of respective caps (5) on which to and conveyor component advance the containers (2) and the relative caps (3); a motor (6) associated with the carrier and conveyor component (5), by which the selfsame component (5) is set in rotation about a respective primary axis (5a); a plurality of capping assemblies (11) associated with the carrier component (5), each positioned above a corresponding container (2) and capable of movement vertically between a first position, distanced from the respective container (2), and a second position actively engaging the container, wherein each capping assembly (11) presents a gripping mechanism (17) such as can be associated with a relative cap (3) when the corresponding capping assembly (11) is in the second gripping mechanism the position, and rotatable in such a way as to screw the cap (3) onto a threaded neck (4) of the respective container (2) about a respective secondary axis (17a); first drive means (14) presenting a plurality of primary electric motors (14a), each one of which associated with a respective capping assembly (11) by which the single in motion be set capping assemblies (11)can another; independently of vertically, one drive means (18) presenting a plurality of secondary electric motors (18a), each one of which associated with a respective gripping mechanism (17) by which

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the single gripping mechanisms (17) can be set in rotation one independently of another; and an electronic controller device (40) connected to each of the primary electric motors (14a) and the secondary electric motors (18a); characterized in that it further comprises a processing block (41) by means of which to vary the operating parameters of each primary electric motor (14a) and each secondary electric motor (18a) according to the dimensions of the respective containers (2).

- 2) A unit as in claim 1, wherein the carrier component (5) comprises:
- a drum (8) associated with the motor (6) and rotatable about the primary axis (5a);
- a base (9) associated with the bottom of the drum (8), on which to stand the containers (2);
 - a platform (10), associated with the top of the drum (8) and facing the base (9), to which the capping assemblies (11) are mounted in a circumferential formation.
 - 3) A unit as in claim 2, wherein each capping assembly (11) comprises a rod (12) inserted slidably through a relative guide (13) afforded by the platform (10), extending longitudinally in coaxial alignment with

the secondary axis (17a) and presenting a first end (12a) with which the respective gripping mechanism (17) is associated, and a second end (12b) opposite to the first end (12a).

- 4) A unit as in claim 3, wherein each primary electric motor (14a) occupies a position coinciding with the second end (12b) of the rod (12) and above the platform (10).
- 5)A unit as in claim 4, wherein each primary electric

 motor (14a) comprises a shaft (15) rotatable about a

 respective axis perpendicular to the secondary axis

 (17a), and a gear (15a) keyed to the shaft (15).
 - 6)A unit as in claim 5, wherein each rod (12) presents a rack (16) extending longitudinally along the respective second end (12b) and engaged in meshing contact by the gear (15a) of each primary electric motor (14a), in such a way that the rod (12) can be set in motion vertically by rotation of the gear (15a).
- 7)A unit as in claims 3 to 6, wherein each secondary electric motor (18a) is mounted between the first end (12a) of the corresponding rod (12) and the gripping mechanism (17) and presents a shaft (19) rotatable about an axis parallel to the secondary axis (17a).

- 8)A unit as in claim 7, wherein the gripping mechanism (17) comprises:
- a gripper (20) attached to the shaft (19) of the respective secondary electric motor (18a), capable of movement between an open condition in which the relative capping assembly (11) is in the first position and a closed condition in which the relative capping assembly (11) is in the second position with the gripper (20) engaging the relative cap (3);
- an actuator (25) by which the gripper (20) is caused to alternate between the open and closed conditions;
- a transmission component (31) interposed between the gripper (20) and the actuator (25), by which motion is relayed from the actuator (25) to the gripper (20).
 - 9)A unit as in claim 8, wherein the gripper (20) comprises:
- a carrier element (21) of substantially cylindrical appearance, associated coaxially with the shaft (19) of the secondary electric motor (18a);
 - a plurality of jaws (22) hinged circumferentially to the cylindrical carrier element (21) and capable

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of movement between a position drawn toward one another, corresponding to the closed condition of the gripper (20), and a position spread apart from one another, corresponding to the open condition of the gripper (20).

10)A unit as in claim 9, wherein each jaw (22) presents a substantially curved appearance and is identifiable as having a first end (22a) furnished with a following roller (23), a second end (22b) opposite to the first end (22a), furnished with a contact element (24) designed to engage the cap (3), and an intermediate portion (22c) disposed between the first end (22a) and the second end (22b) and hinged to carrier element (21).

- 11) A unit as in claim 8, wherein each transmission component (31) comprises a plunger (32) of substantially frustoconical geometry coaxially encircling and slidable along the shaft (19) of the secondary electric motor (18a), and a mechanical linkage (33) coupled rigidly to the plunger (32).
 - 12)A unit as in claim 11, wherein the plunger (32) presents a downwardly tapering outer surface (32c), and the following roller (23) of each jaw (22) rolls vertically on the selfsame external surface (32c).
- 25 13)A unit as in claim 11, wherein the actuator (25) is a linear actuator coupled to the mechanical

linkage (33) in such a way as to induce a vertical movement of the plunger (32).